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# Two-level model of oscillating electric-field-induced current instability and chaos in n-GaAs

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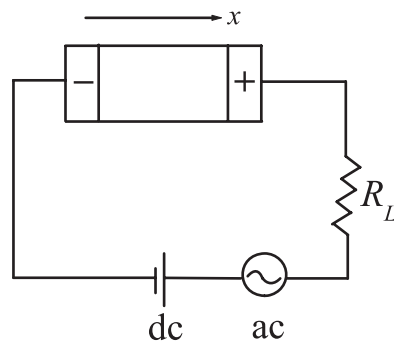
## Abstract

The authors extend the well accepted two-impurity-level model by including the time-dependent balance equation of the mean electron energy to illustrate the current instability for an n-GaAs semiconductor device with planar-type contacts when an ac bias  $E_{ac} \sin(2\pi f_d t)$  is added to the applied dc bias  $E_0$ . To avoid any complications arising from photo-excitation, the authors consider the device in the dark condition. The authors inspect the instability patterns either by keeping the magnitude of dc bias and the frequency of ac current fixed but varying the amplitude of ac bias or by fixing the amplitude and the frequency of ac bias but changing the dc bias. The results of numerical simulations are demonstrated in detail and the system's bifurcating to chaos via several period-doubling routes can be clearly seen in both cases. The bifurcation maps described as a function of the ac drive amplitude  $E_{ac}$  or the dc electric field across the sample  $E_{dc}$  preserve the main features of the experimental observations by Aoki (1992 *Semicond. Sci. Technol.* **7** B474) and Aoki and Yamamoto (1989 *Appl. Phys. A* **48** 111).

## 1. Introduction

Transport instabilities in a semiconductor can be well characterized by a nonlinear dependence of the current density  $J$  upon the electric field  $E$ . This relation is often non-monotonic and displays negative differential conductivity (NDC), which leads to an N-shaped or an S-shaped  $J(E)$  characteristic. In general, devices operated in the NDC region are often unstable against temporal or spatial fluctuations of carrier current density. Examining these instabilities can improve our understanding of the performances of semiconductor devices.

There exist quite a few experimental and theoretical works on this subject for different types of semiconductors. For example, instabilities observed and studied in high purity



**Figure 1.** The circuit equivalent to the experimental semiconductor device with the planar-type contacts.

n-GaAs at 4.2 K include the driven chaos induced by periodically modulated bias voltage [1–4], that by weak perpendicular and/or longitudinal magnetic fields [5–13], and the self-generated chaos which is observed under dc conditions and is broadly independent of external conditions [14–24]. We have discussed the magnetic effects in our previous works [25–27]. In this work, we will concentrate on the instability and chaos driven by an oscillating voltage.

Early in 1983, Teitworth *et al* [28] reported the experimental discovery of subharmonic and chaotic behaviours in periodically driven extrinsic Ge photoconductors. The observations were qualitatively interpreted by a theoretical spatially uniform rate-equation model with a time-dependent current produced by modulated far-infrared (FIR) illumination [29]. Also, Aoki *et al* have investigated periodically driven oscillatory instabilities on n-GaAs [1–4]. Under the so called dark condition (for which external light is completely shielded) at 4.2 K, the  $I$ – $V$  curve of the n-GaAs exhibits a dc stable hysteresis. The nonlinear response of a periodically driven current instability has been investigated by applying a dc + ac bias. With the amplitudes larger than the hysteresis width, they observed various types of frequency locking and chaos when the load line was biased in the hysteresis region [2–4]. The period-doubling bifurcations were found by varying either the magnitude of the dc bias or that of ac bias. They employed a phenomenological one-level impact-ionization model [30–32] to study these findings theoretically. In an alternative way, we would like to adopt Schöll’s two-impurity-level model, with the assumption of spatial homogeneity, to discuss the driven instability phenomena at helium temperatures.

Our computer simulation for the experimental equivalent circuit shown in figure 1 with ac bias will be briefly described in section 2. Because Schöll’s two-level model can capture the essential features of SNDC well, we adopt this model to examine ac driven instability. The governing dynamic equations are basically the same as the previous model. For a more accurate description of the SNDC model, we employ the field-dependent and density-dependent electron mobility and furthermore write it in the phenomenological form. We also adopt the energy balance equation, and take into account the temperature dependence of the generation–recombination (GR) coefficients. This is because the presence of impurities plays a crucial role in causing SNDC. At helium temperature the binding energies of the impurities for free carriers are larger than their thermal energy. Thus, all of the carriers tend to be trapped by the impurities. Although thermal ionization of the electrons in the impurity sites to the conduction band is not possible, the trapped electrons can be ionized to the conduction band by the accelerated free electrons that are driven by an external electric field (called impact ionization). Therefore, the free carriers may be captured by the ionized impurity sites or be generated through the impact

ionization upon the trapped electrons. Based on the above arguments, the transport properties of semiconductors are seriously affected by the generation and recombination of the free carriers between the conduction band and the impurity levels. The impact ionization coefficients  $X_1$  and  $X_1^*$  as well as the capture coefficient  $T_1^S$  have been calculated from Monte Carlo simulation by Scholl's group [33, 34] and furthermore expressed in terms of the electron temperatures and carrier density by fit functions. For the impact ionization coefficients we basically adopt the lucky-electron model [35] and express the dependence of the impact ionization coefficients upon the electron density and electric field through the electron temperatures and electric field. For the capture coefficient  $T_1^S$ , a form similar to that in [34] has been used to reflect the enhancement characteristic near the breakdown field where the low frequency oscillations are expected.

Since the current filament is dc unstable under weak photo-excitation, to avoid further complications, here we consider the device at the dark condition so that the oscillatory behaviour under photo-excitation can be ignored. Based on the theoretical formulation, the numerical simulations are performed. We either keep the magnitude of the dc bias and the ac frequency constant but vary the amplitude of the ac bias, or fix the amplitude and the frequency of the ac bias but alter the dc bias to examine the instabilities. From our simulations under these two circumstances, we do obtain oscillatory instabilities bifurcating to chaos, as will be displayed in section 3 in detail. Simulation results presented here in phase portraits, in power spectra, and in bifurcation maps show a period doubling cascade to chaotic oscillation for increasing sinusoidal drive amplitude  $E_{ac}$  and dc bias  $E_0$ .

## 2. Model

In the two-impurity-level model for n-GaAs, the carrier density  $n$  in the conduction band is governed by the generation–recombination (GR) process in which an electron in the ground or the first excited state of the impurity may be thermally or impact ionized to the conduction band and may then recombine with a donor having an empty state [14, 36]. The electron density  $n$  in the conduction band, the ground level density  $n_{t_1}$  and the first excited level density  $n_{t_2}$  can be expressed through the GR rate equations

$$\dot{v} = \phi(v, v_{t_1}, v_{t_2}, E) \quad (1)$$

$$\dot{v}_{t_i} = \phi_{t_i}(v, v_{t_1}, v_{t_2}, E), \quad i = 1, 2 \quad (2)$$

with  $v = n/N_D^*$ ,  $\dots$ , etc,  $N_D^* = N_D - N_A$  being the effective doping concentration,  $N_D$ ,  $N_A$  the donor and the acceptor concentrations respectively,  $E$  the electric field, and the dot denoting the time derivative. The rate functions  $\phi$  and  $\phi_{t_i}$  can be written as [14, 37]

$$\phi(v, v_{t_1}, v_{t_2}, E) = X_1 N_D^* v v_{t_1} + (X_1^S + X_1^* N_D^* v) v_{t_2} - T_1^S N_D^* (N_A/N_D^* + v) v, \quad (3)$$

$$\phi_{t_1}(v, v_{t_1}, v_{t_2}, E) = -(X^* + X_1 N_D^* v) v_{t_1} + T^* v_{t_2}, \quad (4)$$

with  $v_{t_2} = 1 - v - v_{t_1}$  from the conservation of charge. Hence in an explicit GR model for low temperature n-type GaAs, the transition rates  $\phi$ ,  $\phi_{t_1}$ , and  $\phi_{t_2}$  between the levels must satisfy  $\phi + \phi_{t_1} + \phi_{t_2} = 0$ . The magnitudes of the GR coefficients at 4.2 K, liquid-helium temperature, are given in table 1. These coefficients may vary with various factors, such as changes of the electron temperature  $T_e$ , applications of external electric field, and so on.

Let us consider the experimental equivalent circuit shown in figure 1 where a static and an ac oscillating electric field are applied in the  $x$  direction,  $\mathbf{E}_s = (E_0 + E_{ac} \sin(2\pi f_d t))\hat{\mathbf{x}}$ . Except this, no magnetic or any other field is present. The ac electric field gives rise to an oscillator impedance  $Z$ . Consequently, in the presence of the oscillator the impedance of the equivalent

**Table 1.** The parameter values corresponding to n-GaAs at 4.2 K for the two-level generation-recombination model studied in this paper.

Parameter	Value
$T^*$	$3.45 \times 10^6 \text{ s}^{-1}$
$X_1^{s0}$	$6.9 \times 10^5 \text{ s}^{-1}$
$X^*$	$1.03 \times 10^6 \text{ s}^{-1}$
$X_1^0$	$6.9 \times 10^{-7} \text{ cm}^3 \text{ s}^{-1}$
$X_1^{*0}$	$1.38 \times 10^{-5} \text{ cm}^3 \text{ s}^{-1}$
$l$	$1.0 \times 10^{-3} \text{ cm}$
$e_1$	$6.6 \times 10^{-7} \text{ cm}^3 \text{ s}^{-1}$
$g_1$	$8.0 \times 10^{-6} \text{ cm}^3 \text{ s}^{-1}$
$(e_2, e_3)$	$(2.3, -0.095)$
$(g_2, g_3)$	$(-0.265, 1.254)$
$(v_{th}, q_1)$	$(0.07, 0.693)$
$N_A/N_D^*$	0.3
$r_2$	2.3
$\mu_0$	$2.5 \times 10^4 \text{ cm}^2 \text{ V}^{-1} \text{ s}^{-1}$
$v_s$	$1.25 \times 10^5 \text{ cm s}^{-1}$
$T_L$	4.2 K
$\beta_0^2$	$3 \times 10^2$
$v_0$	$5.75 \times 10^{-3}$
$N_D^*$	$2.5 \times 10^{14} \text{ cm}^{-3}$
$\tau_0$	$6.3 \times 10^{-11} \text{ s}$
$1/\gamma_d$	$9.1 \times 10^{-7} \text{ s}$

circuit becomes  $Z_{eq} = R_L + Z$  with  $R_L$  the load resistance. The dynamical equation for the drift electric field,  $\mathbf{E} = E\hat{x}$ , can be written as

$$\dot{E} = -\gamma_d \left( -E_s + E + \frac{AZ_{eq}}{L} J \right) \quad (5)$$

with the current density

$$J = evN_D^* v_d \quad (6)$$

where  $1/\gamma_d$  is the effective dielectric relaxation time, and  $L$  and  $A$  are, respectively, the separation between contacts and the cross-sectional area of the sample. In the above equation,  $v_d$  is the drift velocity of the electrons and is generally written as

$$v_d = \mu E. \quad (7)$$

On the lower branch of the S-shaped  $n(E)$  characteristic, the velocity is modelled by the empirical saturable form  $v_d(E) = v_s \arctan(r_2 E)$  with the saturated drift velocity  $v_s$  and the saturation parameter  $r_2$  and the mobility  $\mu_{lo}$  is written as [19, 38]

$$\begin{aligned} \mu_{lo}(E) &= \frac{v_d(E)}{E} \\ &= v_s \frac{\arctan(r_2 E)}{E}. \end{aligned} \quad (8)$$

On the high conductivity branch of the S-shaped  $n(E)$  characteristic, an obvious increase of  $T_e$  with rising electric field, scattering is predominant. The electron mobility  $\mu_{up}$  with density  $n$  at temperature  $T_e$  is given by the Brooks–Herring (BH) formula [39]

$$\begin{aligned} \mu_{up}(T_e, \nu) &= \mu_{BH}(T_e, \nu) \\ &= \mu_0 \left( \frac{T_e}{T_L} \right)^{3/2} \frac{g(\beta_0, \nu_0)}{g(\beta, \nu)}, \end{aligned} \quad (9)$$

with

$$g(\beta, \nu) = (2N_A/N_D^* + \nu)(\ln(1 + \beta^2) - \beta^2/(1 + \beta^2)),$$

$$\beta^2 = \beta_0^2 \left( \frac{T_e}{T_L} \right)^2 \frac{\nu}{\nu_0},$$

where the dimensionless electron density  $\nu_0 = n_0/N_D^*$ , and  $n_0$ ,  $\mu_0$ , and  $\beta_0$  are the electron density, the electron mobility, and the so-called BH coefficient, respectively, under zero electric field at  $T_L$ . The transition from  $\mu_{lo}$  to  $\mu_{up}$  at a certain threshold electron density  $\nu_{th}$  corresponding to the largest value of  $\nu$  on the lower branch may be described by saturated drift velocity. Therefore the mobility covering the entire range in  $\nu$  is represented by

$$\mu(T_e, E, \nu) = \frac{1}{2} \{ [\mu_{lo}(E) + \mu_{up}(T_e, \nu) + [\mu_{lo}(E) - \mu_{up}(T_e, \nu)] \tanh[(2 \log_{10}(\nu_{th}/\nu))] \} \quad (10)$$

For a more accurate description of the two-level model, we consider the energy balance equation. During the GR processes the electron temperature  $T_e$  will increase and can be determined through electron mean energy  $\mathcal{E} = \frac{3}{2}k_B T_e$ , with  $k_B$  being the Boltzmann constant.  $\mathcal{E}$  is directly related to the electric field  $E$  via the energy balance equation [40]

$$\dot{\mathcal{E}} = -(\mathcal{E} - \mathcal{E}_L)/\tau(\mathcal{E}) + e\mu E^2 \quad (11)$$

where  $\mathcal{E}_L = \frac{3}{2}k_B T_L$  is the thermal energy at zero electric field with the lattice temperature  $T_L$ , and  $\tau(\mathcal{E}) \propto \mathcal{E}^{-1/2}$  the energy relaxation time considered theoretically. In line with our previous works [26, 27], equation (11) is also converted to [32]

$$\dot{\bar{T}}_e = -\frac{1}{\tau_0} [\bar{T}_e^{1/2} (\bar{T}_e - 1)] + \frac{2e}{3k_B T_L} \mu E^2 \quad (12)$$

with  $\bar{T}_e = T_e/T_L$ , and  $\tau_0$  the energy relaxation time constant.

On the upper branch, the drift velocity increases obviously as a result of the sharp increase of the electron temperature and density. Since  $T_e$  can be determined from the energy balance equation (11) or (12) and  $\nu$  is related to the electric field by GR rate equations (1) and (2), our  $\mu_{BH}$  in equation (9) used to express the enhancement of the mobility on the upper branch of the  $n(E)$  characteristic is dependent on the electric field implicitly. Thus solving the coupled differential equations (1), (2), (5), and (12) enables us to examine the cross-over instability for n-type GaAs due to the effects from the electric field  $E$  including the oscillating ac field, our present main interest, and the carrier temperature  $T_e$  variation.

An essential part of the two-level model is the generation and recombination of the free carrier between the conduction band and the impurity levels. Besides explicitly appearing in the differential equations, the electron density and electric field may also implicitly be embedded in the GR coefficients. We apply Schöll's group's works [33, 34] to account for the GR coefficients' electric field and electron density dependence, as to be briefly described in the following.

For the impact-ionization coefficients  $X_1$  and  $X_1^*$ , basically we adopt the electric field and binding energy dependent lucky-electron model [35]. But as  $E$  goes higher than the breakdown field, these  $X_1$  and  $X_1^*$  behave differently towards  $T_e$  [33]. Since both  $T_e$  and  $X_1$  show similar behaviours as  $E$  varies [33, 34], a factor  $\delta(T_e)$  is multiplied to the cross section of  $X_1$  when the temperature increases,

$$\delta(T_e) = 1 + \lambda T_e/T_L, \quad (13)$$

where  $\lambda$  is an adjustable parameter and is taken to be 0.06. Therefore  $X_1$  becomes

$$X_1(E, T_e) = \delta(T_e) X_1^0 e^{-\varepsilon_b/elE}. \quad (14)$$

On the other hand, because the excited state's ionization energy is much smaller than the ground state's,  $X_1^*$  shows a very weak dependence on  $T_e$  [33]. Hence we keep  $X_1^*$  the same form as that in the lucky-electron model [35],

$$X_1^*(E) = X_1^{*0} e^{-\varepsilon_b^*/e l E}, \quad (15)$$

with coefficients  $X_1^0$  and  $X_1^{*0}$  and mean free path  $l$  being given in table 1, and  $\varepsilon_b = 6.0$  and  $\varepsilon_b^* = 1.5$  meV the impurity ground and first excited state binding energies for n-GaAs.

Generally, the capture rate decreases monotonically with the field except at the onset of the upper branch, where  $T_1^s$  increases because strong impact ionization scatters many carriers back to the band minimum, from where they can recombine with high probability. The capture coefficient  $T_1^s$  is represented by [34]

$$\begin{aligned} T_1^s(T_e, \nu) &= \frac{4}{5} T_1^{s,lo}(T_e) + \frac{1}{2} \{ [T_1^{s,up}(T_e) + T_1^{s,lo}(T_e)] + [T_1^{s,up}(T_e) \\ &\quad - T_1^{s,lo}(T_e)] \tanh[\log_{10}(\nu/\nu_{th})^{0.8}] \}, \\ T_1^{s,up}(T_e) &= e_1 \exp[e_2(T_e/T_L - q_1)^{e_3}], \\ T_1^{s,lo}(T_e) &= g_1 \exp[g_2(T_e/T_L)^{g_3}] \end{aligned} \quad (16)$$

with parameters  $\nu_{th}$ ,  $q_1$ ,  $e_i$ ,  $g_i$ ,  $i = 1, \dots, 3$ , being defined in [34].

On the part of the thermal ionization coefficient  $X_1^s(T_e)$ , we take into account the effect of the Boltzmann factor and write it as

$$X_1^s(T_e) = X_1^{s0} e^{\varepsilon_b^s(1/k_B T_L - 1/k_B T_e)}, \quad (17)$$

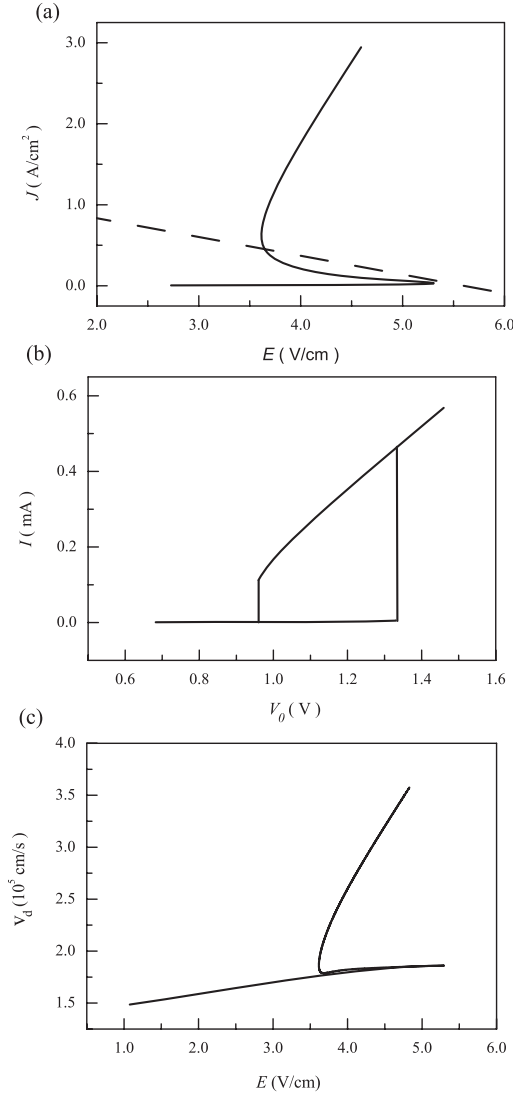
where  $X_1^{s0}$  is the thermal ionization coefficient at lattice temperature  $T_L$ .

### 3. Simulations and numerical results

We now represent the results of numerical simulations for the two-impurity-level model with the field-dependent and temperature-dependent electron mobility and GR coefficients, to describe the experimental measurements [1–4] performed at 4.2 K under dark conditions for a high purity n-GaAs with a typical rectangular cross-section area  $A = 1.8 \times 10^{-4}$  cm<sup>2</sup>, and the spacing between the planar-type contacts  $L = 2.5$  mm.

We first solve equations (1), (2) and (12) under their stationary state conditions ( $\dot{\nu} = \dot{\nu}_{i_1} = \dot{T}_e = 0$ ), making use of the  $E$ - and  $T_e$ -dependent GR coefficients mentioned in the previous section. We then obtain the static S-shaped  $J$ - $E$  characteristic as shown in figure 2(a). Referring to the reasonable material parameters for n-type GaAs [14, 34], the numerical parameters used in the calculation are tabulated in table 1. As a dc bias voltage  $V_0$  is applied across a series resistance of the GaAs sample and a load resistor  $R_L$ , a specified load line is determined by  $J = (E_0 - E)/d$ , with  $d = AR_L/L$ ,  $E_0 = V_0/L$ , and  $E = V/L$ ,  $V$  being the voltage across the sample. The slope of the load line,  $dJ/dE = -1/d$ , remains a constant once  $R_L$  is specified, but the position of the horizontal intercept varies with the applied field  $E_0$  (or with the dc bias voltage  $V_0$ ). Hence by setting  $R_L = 500 \Omega$  in our numerical simulations we have the load-line condition as  $d = 0.36$  cm V A<sup>-1</sup>. The load line is biased on the upper branch or lower branch or in the NDC region of the  $J$ - $E$  curve, showing no spontaneous relaxation oscillation. The stable hysteresis is formed as shown in figure 2(b) if  $J$  is assumed homogeneous over the sample's cross section  $A$ .

Steady-state solution of the drift velocity is shown as a function of  $E$  in figure 2(c). The drift velocity  $v_d$  generally increases with the field  $E$ . A strong increase of  $v_d$  with rising electric field occurs on the high conductivity branch as opposed to only a slight increase on the low conductivity branch. The remarkable increase in  $v_d$  on the upper branch is apparently caused by the screening effect of the ionized impurity scattering in the BH mobility formula (9).



**Figure 2.** The  $J$ - $E$  characteristic (a), the corresponding  $I$ - $V$  curve (b) for an S-shaped NDC GaAs, when it is connected in series with a dc bias and a load resistor, and the drift velocity  $v_d$  (c). In (a) the dotted line denotes a load line with the load line condition  $d^* = AZ_{\text{eq}}/L = 4.32 \text{ cm V A}^{-1}$ .

This reveals the same trend as the simulated drift velocity in [33] and keeps a consistent characteristic of the anomalously high mobilities observed inside the current filaments in n-GaAs, as compared to the much lower mobilities outside [41].

Now turn on the ac bias so that the electric field across the GaAs sample and the load resistor  $R_L$  is  $E_s = E_0 + E_{\text{ac}} \sin(2\pi f_d t)$ . The impedance of the equivalent circuit  $Z_{\text{eq}}$  now includes  $R_L$  and the oscillator impedance  $Z$ . Choosing  $Z \sim 5.5 \text{ k}\Omega$ , we have  $Z_{\text{eq}} = 6 \text{ k}\Omega$ . Consequently, in the presence of the oscillator (ac bias), the load line becomes  $E = E_0 - d^* J$  with the load line condition  $d^* = AZ_{\text{eq}}/L = 4.32 \text{ cm V A}^{-1}$ . Therefore, we pick up the operating point  $(E_i, J_i)$  from the intersection of the  $J$ - $E$  characteristic with the load line, as



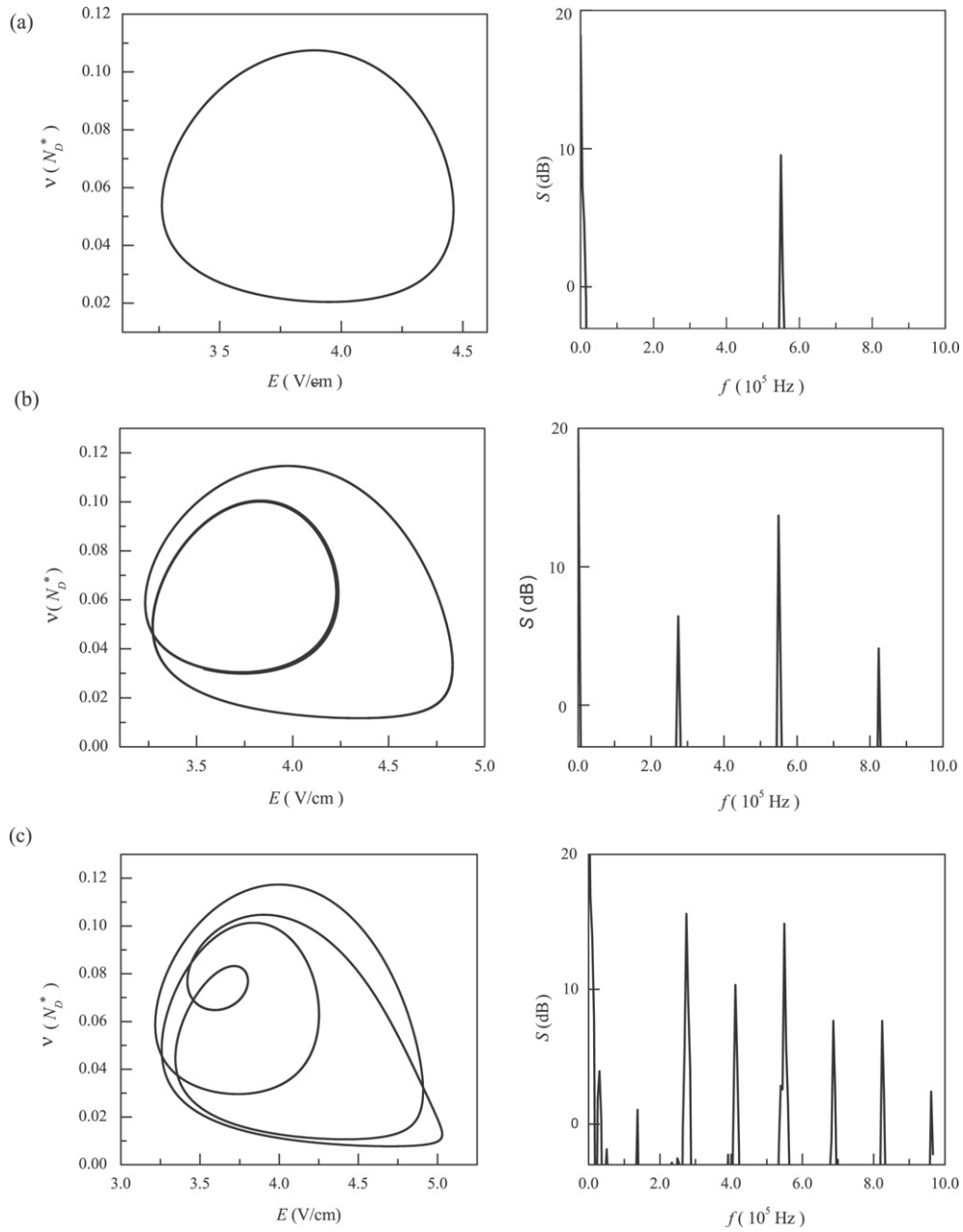
the dotted line shown in figure 2(a) with the intersection at  $E_0 = 5.599985 \text{ V cm}^{-1}$  biased in the NDC region of the  $J$ - $E$  characteristics. The system is stable without ac bias.

Since the energy relaxation time  $\tau_0 (\sim 10^{-10} \text{ s})$  is shorter than the effective dielectric relaxation time  $1/\gamma_d (\sim 1 \text{ } \mu\text{s})$ , the energy balance assumes a quasi-steady state almost instantaneously, determining  $\mathcal{E}(T_e)$  as a function of the electric field  $E$ , which varies slowly according to equation (5), and the dynamics is dominated by the dielectric field relaxation. By specifying  $f_d = 5.5 \times 10^5 \text{ Hz}$  and increasing gradually the magnitude of the amplitude of the ac bias  $E_{ac}$  from 0.8 to 0.975  $\text{V cm}^{-1}$  when solving equations (1), (2), (5), and (12), we are able to see the period-doubling chaotic bifurcation sequence as shown in figures 3(a)–(e). Plotted in the left column of figures 3(a)–(e) are the phase portraits of the conduction electron concentration  $\nu$  versus the electric field  $E$  for period 1, period 2, period 4, period 8, and chaos with  $E_{ac}$  set to be 0.8, 0.9, 0.94, 0.944, and 0.945  $\text{V cm}^{-1}$ , respectively. Their corresponding Fourier power spectra of  $\nu(t)$  are shown in the right column of figures 3(a)–(e), where a clear peak at  $f = f_d$  can be seen from the right part of figure 3(a) for a period-1 limit cycle. Increasing  $E_{ac}$  slightly makes it bifurcate to period-2 oscillation with a subharmonic component at  $f_d/2$ , and then period-4 oscillation with an additional subharmonic component at  $f_d/4$ , as in figures 3(b) and (c), respectively. At  $E_{ac} = 0.944 \text{ V cm}^{-1}$  a period-8 oscillation arises, as in the power spectrum of figure 3(d), and subharmonic components at  $f_d/2$ ,  $f_d/4$  and  $f_d/8$  can be clearly seen. Finally, chaos appears in figure 3(e) when  $E_{ac}$  is raised to or beyond 0.945  $\text{V cm}^{-1}$ . The above described behaviours as a function of  $E_{ac}$  in the NDC regime are clearly displayed in the bifurcation map as shown in figure 4, where  $\nu_{max}$  is the maximum value of the electron density for the conduction band. In the map, the oscillations with more periods appear in a shorter interval of  $E_{ac}$ , for example, period-2 oscillations existing in  $0.885 \text{ V cm}^{-1} \leq E_{ac} < 0.924 \text{ V cm}^{-1}$ , period-4 oscillations existing in  $0.924 \text{ V cm}^{-1} \leq E_{ac} < 0.943 \text{ V cm}^{-1}$ , while period-8 oscillations in a much shorter one,  $0.943 \text{ V cm}^{-1} \leq E_{ac} < 0.945 \text{ V cm}^{-1}$ . Each figure in figures 3(a)–(e) is a chosen example in each corresponding interval. Beyond the appearance of chaos, further increasing  $E_{ac}$  to around 0.967  $\text{V cm}^{-1}$ , we also obtain period-5 oscillations. The bifurcation pattern described here is similar to that observed in [3].

To show the rich structure of the bifurcation routes to chaos in the NDC region of the  $J$ - $E$  curve and to give a more intuitive understanding, we also choose the dc electric field across the sample  $E_{dc}$ , related to the applied static electric field  $E_0$  as  $E_{dc} = E_0 - d^*J$ , as the control parameter, while  $E_{ac}$  and  $f_d$  are kept as constants. With an appropriate dc bias  $E_0$  in the NDC branch of the  $J$ - $E$  curve, we can find the stable operating point as stated previously, and  $E_{dc}$  can thus be determined. In our numerical simulation, we have the magnitude of  $E_{dc}$  varied from 3.6375 to 3.6477  $\text{V cm}^{-1}$  with the same load-line condition  $d^* = 4.32 \text{ cm V A}^{-1}$ . Equations (1), (2), (5), and (12) are now solved by fixing the amplitude  $E_{ac}$  at a relatively large value of 0.945  $\text{V cm}^{-1}$  and driving frequency at  $f_d = 5.5 \times 10^5 \text{ Hz}$ . The results are plotted in figure 5, with  $\nu_{max}$  being defined in the same way as that in figure 4. In the figure, we can clearly see the de-stability of the period-1 limit cycle via bifurcation to chaos as the control parameter  $E_{dc}$  varies. Our bifurcation map shown in figure 5 is similar to the one observed experimentally in [4].

#### 4. Conclusion

Nonlinear instabilities induced by oscillating voltages imposed on semiconductor devices have been observed experimentally. Studying the rich structures of such phenomena can give us a better understanding on the performance of the semiconductors. In this work, we extend the two-impurity-level model by including the time-dependent balance equation of the mean



**Figure 3.** Left column, phase portraits of the conduction electron concentration  $v(t)$  versus the electric field  $E(t)$ ; right column, power spectrum  $S(f)$  of  $v(t)$  for the driving frequency  $f_d = 5.0 \times 10^5$  Hz and five increasing drive amplitudes: (a)  $E_{ac} = 0.8 \text{ V cm}^{-1}$ , (b)  $E_{ac} = 0.9 \text{ V cm}^{-1}$ , (c)  $E_{ac} = 0.94 \text{ V cm}^{-1}$ , (d)  $E_{ac} = 0.944 \text{ V cm}^{-1}$ , and (e)  $E_{ac} = 0.945 \text{ V cm}^{-1}$ .

energy per carrier to inspect theoretically the driven instability from the n-GaAs semiconductor device with the planar-type contacts as shown in figure 1 under the series connection of the ac and the dc sources. The effects from the electric field and the electron temperature variation on

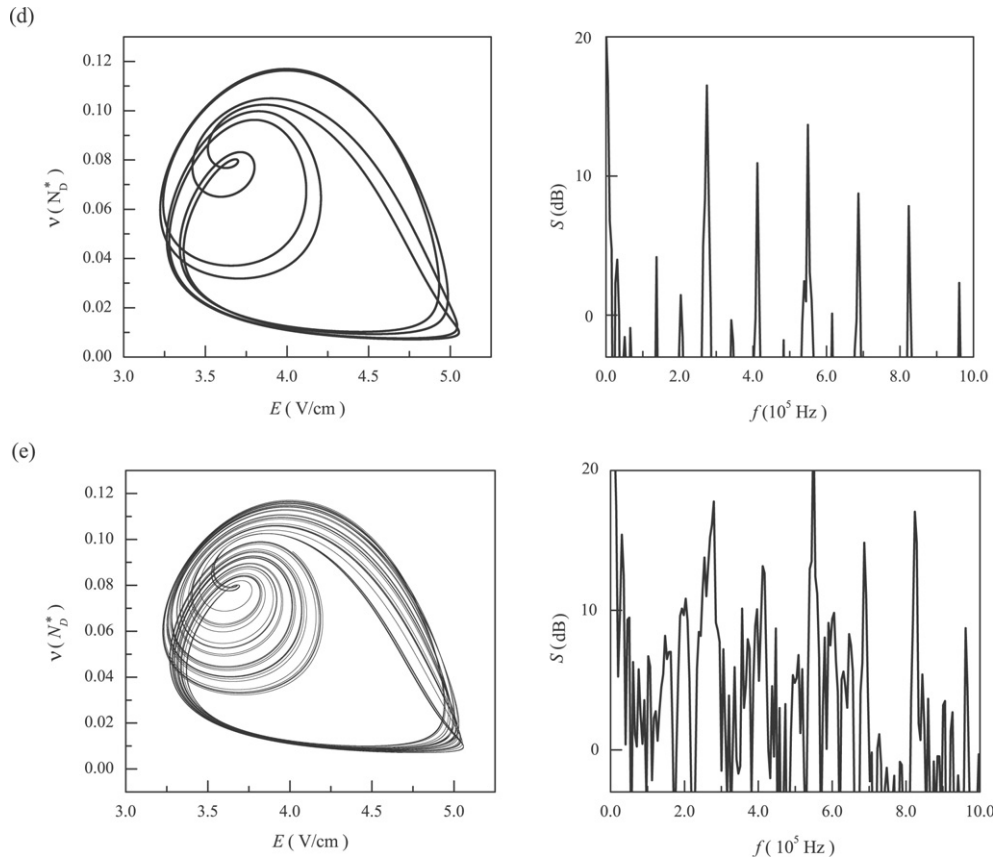


Figure 3. (Continued.)

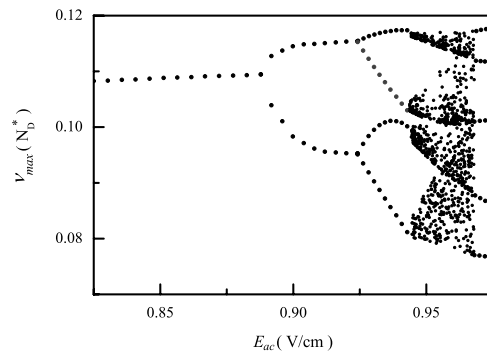
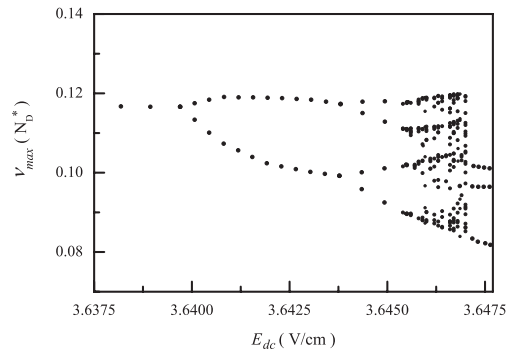


Figure 4. Bifurcation map of the conduction electron concentration maxima  $v_{max}$  versus the ac drive amplitude  $E_{ac}$ , for the dc bias  $E_0 = 5.599985 \text{ V cm}^{-1}$ .

the rate equations and the GR coefficients are taken into account here. Two different functions  $\mu_{up}$  and  $\mu_{lo}$  have been used to express the enhancement of the mobility on the upper branch, where  $\mu_{up}$  is supported by the BH formula to take into account the screen effect of the ionized-impurity scattering, and  $\mu_{lo}$  is retained in the empirical saturation form. To proceed with



**Figure 5.** Bifurcation map of the conduction electron concentration maxima  $v_{\max}$  versus the dc electric field across the sample  $E_{\text{dc}}$ , for the ac bias amplitude  $E_{\text{ac}} = 0.945 \text{ V cm}^{-1}$  and the frequency  $f_{\text{d}} = 5.5 \times 10^5 \text{ Hz}$ .

numerical simulations, we first find the stable hysteresis loop ( $I$ - $V$  curve) under the dc bias and the dark conditions. In order to observe chaos, we set the amplitudes of the ac voltage to be larger than the hysteresis width and appropriately bias the load line in the hysteresis region to choose the operation points which are stable without ac bias. We then solve the coupled differential equations of the GR rate equations, the energy balance equation, and the dynamic equation for the drift electric field. The numerical computations are performed under the schemes of (i) keeping the dc voltage and the ac frequency constant but gradually adjusting the ac amplitude and (ii) fixing the amplitude and the frequency of the ac source and varying the dc voltage. For both schemes, we can obtain clear current oscillating to chaos via period doubling routes. We demonstrate the results in phase portraits and their Fourier power spectra as well as bifurcation maps in details. Our results preserve the main features of experimental observations [1–4]. Aoki *et al* have used the feature that the system undergoes period-doubling bifurcations to chaos under dc + ac bias to propose novel applications such as a deterministic noise amplifier and a chaos memory device [42–44]. Our model shows a smooth period-doubling bifurcation as a function of  $E_{\text{ac}}$  and that of  $E_{\text{dc}}$ , but still has some discrepancies in comparing with the experimental result, which has more complicated routes to chaos than the result of our simulation. Further detailed analysis on electronic turbulence requires progression of the spatiotemporal model simulation. We are currently heading in this direction.

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